

Amendments to the Specification:

On page 1, after the title and prior to the heading "Field of the Invention," please insert the following text:

CROSS-REFERENCE TO RELATED APPLICATIONS

This application claims the benefit of International Patent Application No. PCT/US2004/039148, filed November 22, 2004, which claims the benefit of Australian Patent Application No. AU2003906642, filed November 24, 2003, both of which are incorporated by reference herein in their entirety.

On page 1, please amend the first full paragraph under the heading "Background of the Invention" as shown below:

The need for a mechanism that enables the adjustment of the height of a keyboard support surface relative to a fixture is well recognised. My Australian Patent No. 65578/90 and my United States of America Patent No, 5,292,097, disclose [[are]] improved four-bar or four element parallelogram mechanisms that allow a support surface height to be adjusted relative to a fixed surface. These mechanisms were of a type which enabled a working platform to be attached to a moveable element or bracket, which in turn was pivotally connected to one end of a pair of substantially parallel link elements, which in turn were pivotally connected at their other end to a fixed element or bracket, which was capable of being affixed or otherwise mounted to the underside of a desk-top. A feature of these mechanisms was their ability to maintain a substantially parallel relationship between the moveable element or bracket and the fixed element or bracket throughout the height adjustment range.

On page 1, please amend the last full paragraph as shown below:

In many four-bar linkage mechanisms, the amount of rotation of the moveable bracket relevant to the fixed bracket is limited by the overlapping and interference of the link arms. Also in many four-bar linkage mechanisms, the rotational movement of the moveable bracket relative to the fixed bracket may require protection guards to be [[35]] positioned to avoid the creation of pinch points. Also in many adjustable support mechanisms, the linkage arms and brackets may

intrude significantly into knee-hole space and otherwise interfere with the operator using the attached support platform.

On page 2, please amend the first full paragraph as shown below:

It is to be understood that, if any prior art publication [[S]] is referred to herein, such reference does not constitute an admission that the publication forms a part of the common general knowledge in the art, in Australia or any other country.

On page 2, please amend the paragraph beginning with the text “a linking member...” as shown below:

a linking member coupled to the connecting member so as to be movable in relation to the connecting member, [[25]] wherein the linking member is arranged to engage the bracket: and the second bracket such that pivotal movement of the first bracket in a first rotational direction is related to movement of the linking member, which is in turn related to pivotal movement of the second bracket also in the first rotational direction.

On page 11, please amend the paragraph beginning with “Referring to Figures 6 and 7...”, as shown below:

Referring to Figures 6 and 7, this embodiment of the adjustable support mechanism 10 is similar to the previous embodiment although in this case there are some differences to the screw drive 34 and the linking 18, In this embodiment the screw drive 34 has a series of parallel, grooves 24 in the cylinder 20 that do not make a complete rotation of the screw drive 34. The linking member 18 has three follower pins 26 each of which project into a corresponding one of the three grooves 24 [[€if]] of the screw drive 34.

On page 11, please amend the paragraph beginning with “The linking member...”, as shown below:

The linking member 18 has a hole 46 there through near each of the ends. A securing pin 42 passes through each hole 46 to couple the linking member 18 to the connecting member 16 in a manner which allows the linking member 18 to transversely slide along the securing pins 42 in

relation to the connecting member 16. But for the follower pins 26 the linking member 18 would be ~~tree~~ free to slide along the length of the securing pins 42. The securing pins 42 pass through a corresponding hole 44 in the side walls of the connecting member 16 and are fixed to the connecting member 16.

On page 13, please amend the paragraph beginning with "In Figure 11A...", as shown below:

In Figure 11A an alternative coupling arrangement between the screw drive 34 and connecting member 18 is shown. In this embodiment connecting member 18 pivots about axle 19 which extends from the back plate 68 of the connecting member 16. In this embodiment the screw drive 34 includes helical mesh teeth 27 and the follower is in the form of helical mesh teeth 25. The teeth 27 and 25 form a helical crossed gear. An example of a helical crossed gear is shown in Figure ~~[[118]]~~ 11B. The linking member 18 may in effect be formed by removing the superfluous side portions above and below the lines indicated as X - X in Figure 11B.

On page 17, please amend the paragraph beginning with "A skilled addressee...", as shown below:

A skilled addressee will realise that the present invention has ~~advantageous~~ advantages over the prior art. In addition to the advantages mentioned above, in comparison to the some prior art support mechanisms, a support mechanism according to the present invention allows a greater range of movement of the second bracket relative to the first bracket.

On page 17, line 9, please amend the paragraph beginning with "A person skilled in the art...", as shown below:

A person skilled in the art will realise that modifications and variations may be ~~mad~~ made to the present invention without departing from the basic inventive concept. Some of the modifications and variations have been described herein, although it will be appreciated that other variations may be made which include further alternatives to the locking mechanism, the arrangement of the linking member in relation to the connecting member as well as variations to the angle adjustment means.

On page 17, please amend the paragraph beginning with “Such modifications...”, as shown below:

Such modifications and variations are intended to all within the scope of the present invention, the nature of which is to be determined from the foregoing description [[15]] and appended claims.